# THE FORM OF LATERAL VISCOSITY IN ATMOSPHERIC FLOWS

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# THESIS

The Form of Lateral Viscosity
in Atmospheric Flows

bу

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# The Form of Lateral Viscosity in Atmospheric Flows

bу

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#### ABSTRACT

Long term numerical integrations were performed on a two-dimensional model utilizing the barotropic vorticity equation including a space-and time-dependent forcing function and a laminar-type viscosity term. Three different forms of the laminar type viscosity or dissipation term were used. A comparison was made of the effects these different dissipation terms had on the time-dependence of total kinetic energy, total enstrophy, and total gradient of vorticity squared, the spectral distribution of kinetic energy and enstrophy, and the stream function field. A difference of behavior of all the above variables was found for each form of dissipation.



# TABLE OF CONTENTS

I.	INTRODUCTION	9
II.	MATHEMATICAL MODEL	11
III.	FORMS OF DISSIPATION	13
IV.	DISCUSSION OF RESULTS	15
v.	CONCLUSIONS	20
APPEND	IX A - COMPLETE DESCRIPTION OF THE MODEL	23
APPEND	OIX B - FINITE DIFFERENCE EQUATIONS	25
APPEND	IX C - RELAXATION TECHNIQUE	27
APPEND	OIX D - TIME STEP SCHEMES	29
LIST O	F REFERENCES	6 2
INITIA	L DISTRIBUTION LIST	63
FORM D	nn 1473	6.5



# LIST OF FIGURES

1.	Grid for the model	23
2.	Total kinetic energy vs. time for the zero forcing and zero dissipation case and for A = constant form of dissipation	30
3.	Total kinetic energy vs. time for the $A_S$ form of dissipation with gamma = .5, .2, and $S$ .13	31
4.	Total kinetic energy vs. time for the $A_L$ form of dissipation with gamma = .5 and .2	32
5.	Total enstrophy vs. time for the zero forcing and zero dissipation case and for A = constant form of dissipation	33
6.	Total enstrophy vs. time for the $A_S$ form of dissipation with gamma = .5, .2, and .13	34
7.	Total enstrophy vs. time for the A form of dissipation with gamma = .5 and .2 $^{L}$	35
8.	Total gradient of vorticity squared vs. time for the zero forcing and zero dissipation case and for A=constant form of dissipation	36
9.	Total gradient of vorticity squared vs. time for the A <sub>S</sub> form of dissipation with gamma = .5, .2, and .13	37
10.	Total gradient of vorticity squared vs. time for the $A_L$ form of dissipation with gamma = .5 and .2 $^L$	38
11.	Initial spectral distribution of kinetic energy and enstrophy	39
12.	Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the zero dissipation and zero forcing case	40
13.	Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A = constant form of dissipation	41
14.	Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A <sub>S</sub> form of dissipation with gamma = .5	42



15.	Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the As form of dissipation with gamma = .2	4 3
16.	Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A form of dissipation with gamma = .13	44
17.	Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A <sub>L</sub> form of dissipation with gamma = .5	4 5
18.	Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A <sub>L</sub> form of dissipation with gamma = .2	46
19.	Initial stream function field	47
20.	Stream function field at 5 days for zero forcing and zero dissipation case	48
21.	Stream function field at 5 days for A = constant form of dissipation	48
22.	Stream function field at 10 days for zero forcing and zero dissipation case	49
23.	Stream function field at 10 days for A = constant form of dissipation	49
24.	Stream function field at 15 days for zero forcing and zero dissipation case	50
25.	Stream function field at 15 days for A = constant form of dissipation	50
26.	Stream function field at 20 days for zero forcing and zero dissipation case	51
27.	constant form of dissipation	51
28.	Stream function field at 5 days for $A_L$ form of dissipation with gamma = .5 $-L$	5 2
29.	Stream function field at 5 days for $A_L$ form of dissipation with gamma = .2	52
30.	Stream function field at 10 days for $A_L$ form of dissipation with gamma = .5	53



	Stream function field at 10 days for $A_L$ form of dissipation with gamma = .2	53
32.	Stream function field at 15 days for A form of dissipation with gamma = .5	54
33.	Stream function field at 15 days for $A_L$ form of dissipation with gamma = .2	5 4
34.	and the state of t	5 5
35.	Stream function field at 20 days for $A_L$ form of dissipation with gamma = .2	5 5
36.	Stream function field at 5 days for A form of dissipation with gamma = .5	56
37.	Stream function field at 5 days for A form of dissipation with gamma = .2	56
38.	Stream function field at 10 days for A <sub>S</sub> form of dissipation with gamma = .5	57
39.	Stream function field at 10 days for A <sub>S</sub> form of dissipation with gamma = .2S	57
40.	Stream function field at 15 days for A form of dissipation with gamma = .5	58
41.	Stream function field at 15 days for A form of dissipation with gamma = .2S	58
42.	Stream function field at 20 days for A form of dissipation with gamma = .5	59
43.	Stream function field at 20 days for A form of dissipation with gamma = .2	
44.	Stream function field at 5 days for A form of dissipation with gamma = .13	
45.	Stream function field at 10 days for A <sub>S</sub> form of dissipation with gamma = .13	60
	Stream function field at 15 days for A <sub>S</sub> form of dissipation with gamma = .13	
47.	Stream function field at 20 days for A <sub>S</sub> form of dissipation with gamma = .13	61



# LIST OF SYMBOLS

- β derivative of coriolis parameter at mid-latitude
- γ constant coefficients
- ζ vorticity
- ψ stream function
- A coefficient of "eddy diffusion"
- S source term
- t time
- K.E. kinetic energy
- $\frac{\xi^2}{2}$  enstrophy



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### I. INTRODUCTION

With modern computers it is possible to simulate turbulent motion in three dimensions. As a consequence of theoretical studies as well as experimental results, the turbulent processes at work in the three-dimensional case are reasonably well understood. In recent years, however, studies have also been conducted on two-dimensional turbulence as an analogue to the large scale motions of the atmosphere. The behavior of the two-dimensional turbulence parameters is just beginning to be discovered.

The principal distinguishing feature of two-dimensional turbulence is the tendency of its energy-containing eddies to grow indefinitely in scale. In any finite difference model of two-dimensional turbulent flow, therefore, the energy transfer between large scales will be computed more or less correctly. At the scale of the grid interval, how-ever, aliasing errors can transfer energy erroneously to all of the larger scales destroying the sense of the calculation. This problem can be alleviated by the removing of energy from scales near the grid scale. The energy thus "dissipated" is that which would cascade to smaller scales in real flow.

A common procedure in numerical modeling is to parameterize the sub-grid scale dissipation in the form of a diffusion process with an assigned coefficient of "eddy



diffusion", A, as in  $\nabla$  • (A $\nabla \zeta$ ), where  $\zeta$  is the fluid property being dissipated.

The objective of the present work is to compare the behavior of certain properties generated by different forms of the eddy diffusion term in two-dimensional turbulent flow.



#### II. THE MATHEMATICAL MODEL

The principal equation of the model is the barotropic vorticity equation including a space- and time-dependent forcing function and a laminar-type viscosity, written as

$$\frac{\partial \zeta}{\partial t} + J(\psi, \zeta) + \beta \frac{\partial \psi}{\partial x} = S + \nabla \cdot (A\nabla \zeta) \tag{1}$$

The wind velocity is associated with the stream function by the following equation:

$$W = i\left(\frac{\partial \psi}{\partial y} + j\right) \frac{\partial \psi}{\partial x} \tag{2}$$

The vorticity is the laplacian of the stream function,

$$\nabla^2 \psi = \zeta \tag{3}$$

In all of the numerical experiments undertaken in this study, the regime of integration is taken to be a rectangle with cyclic boundary condition in the x direction and free slip boundary conditions on the northern and southern boundaries. (See Appendix A).

The numerical integration of Equation (1) and (3) was performed by first replacing them with a pair of finite difference equations to be solved for the variables prescribed on a cartesian grid. (See Appendix B).

The numerical space-differencing method used on the non-linear terms of Equation (1) is the second-order scheme developed by Arakawa (1966) which conserves kinetic energy and enstrophy within the nonlinear terms. The laplacians in Equations (1) and (3) were approximated by the methods



discussed in Appendix B. Time integration was performed by the explicit centered leapfrog scheme, except for the first step and restarts every 50 time steps by the iterative Euler-backward scheme. (See Appendix D).

The forcing function S used in these experiments was a crude approximation for the baroclinic driving forces in the atmosphere. S was negatively related to the stream function and was scaled to the magnitude of the rate of change of vorticity. (See Appendix A). The source term was set to zero at mid-time in each experiment conducted to study the decay properties of each form of dissipation.

The initial stream field was defined to have components in wave numbers 2, 4, and 6 and of such magnitude as to simulate the 500-mb patterns. (See Appendix A).

The different forms of the dissipation are discussed in the following chapter.



### III. FORMS OF DISSIPATION

In Equation (1), the last term on the right hand side represents a laminar-type viscosity or dissipation and is written as  $\nabla \cdot (A\nabla \zeta)$ . The experiments assumed three different forms of A which represents the coefficient of "eddy diffusion."

In the first form, A was taken to be the constant .5 x  $10^6$  m<sup>2</sup> sec<sup>-1</sup>. This value was used to produce an equilibrium solution of a one-wave stream function field within the time frame of these experiments.

The second form of A was taken to be a function of the wind field as formulated by Smagorinsky (1963) for three-dimensional turbulence:

$$A_{S} = \gamma_{1} |D_{*}| (\Delta x)^{2}$$
 (4)

where D\* is the deformation on the grid  $\Delta x$  and  $\gamma_1$  is a constant.

The deformation is defined as:

$$|D_{\star}| = \sqrt{D_{\mathrm{T}}^2 + D_{\mathrm{S}}^2}$$

where

$$D_{T} = \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y}$$

and

$$D_{S} = \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}$$

The third and final form of A was that proposed by Leith (1969) for two-dimensional turbulence, namely,



$$A_{L} = \gamma_{2} |\nabla \zeta| (\Delta x)^{3}$$
 (5)

Here  $\gamma_2$  is a constant and  $\left|\, \nabla \zeta \,\right|$  is the scalar magnitude of the gradient of vorticity.

The finite difference forms of the above equations may be found in Appendix B.



### IV. DISCUSSION OF RESULTS

Seven experiments were conducted for comparison and evaluation of the different forms of dissipation as follows:

- (1) Equation (1) with the source and dissipation terms removed.
- (2) A constant coefficient for A in Equation (1).
- (3) Smagorinsky's form of A (Equation 4) with  $\gamma_1 = .5$ .
- (4) Smagorinsky's form of A with  $\gamma_1 = .2$ .
- (5) Smagorinsky's form of A with  $\gamma_1 = .13$ .
- (6) Leith's form of A (Equation 5) with  $\gamma_2 = .5$ .
- (7) Leith's form of A with  $\gamma_2 = .2$ .

In each experiment, the time-dependence of total kinetic energy, total enstrophy, and the total magnitude of the gradient of vorticity squared were calculated, along with the spectral distribution of energy and enstrophy. The effects of each dissipation form on these measurements and on typical wave disturbances were of prime interest.

Comparing first the time-dependence of kinetic energy (Figures 2, 3, 4), it was noted that except for the zero dissipation, zero source case there was a tremendous decrease of kinetic energy initially. The order in which this dissipation changed into regeneration was, by experiment numbers, 7,2,3,5,4,6. In general the Leith form halted the initial rapid dissipation of kinetic energy earlier.

The energy in the model at mid-time was, by decreasing order of magnitude, 1,5,7,2,4,3,6. These values were



obviously dependent upon the size of the dissipation term. However, the energy present at end-time was not in the same order as above, 1,5,7,4,3,2,6. This indicated the A = constant form had a greater rate of dissipation than the other forms after the source term was taken out. An interesting point noted was that for both  ${\rm A_L}$  and  ${\rm A_S}$ , the smaller  $\gamma$  terms produced the greater rate of dissipation. This was due to the dependence of both  ${\rm A_L}$  and  ${\rm A_S}$  on the strength of the flow and with the smaller  $\gamma$  the flow was stronger as will be discussed later.

Looking next at the time-dependence of enstrophy (Figures 5,6,7), in each of the experiments it was easily seen that enstrophy was far more conservative than energy. However, the enstrophy dissipated rapidly initially as did the kinetic energy. In the Smagorinsky and Leith forms of A there was a tendency for the enstrophy to stabilize faster for larger values of  $\gamma$ . Leith's form caused a slight growth in enstrophy after the initial drop but once the source was cut off at mid-time enstrophy dissipated slightly. In Smagorinsky's form, enstrophy was more nearly conserved while the source was in Equation (1), but enstrophy had a tendency to be dissipated when the source was turned off. A constant A did not conserve enstrophy.

The final time-dependent term to be considered was the total gradient of vorticity squared (Figures 8,9,10). This term was even more conservative than the two terms considered before. There was a tendency for equilibrium with respect



to  $|\nabla\zeta|^2$  to be reached faster the greater the  $\gamma$  terms. The fastest equilibrium solution was from experiment 6 with experiment 3 following. The experiments in which the total gradient of vorticity squared was most conserved were both Leith forms and the Smagorinsky form with  $\gamma$ =.5, while there were a number of small fluctuations in 2. The deviations noted in the gradient of vorticity squared terms seemed to be more like step functions than smooth curves after the initial level-off of values in all experiments other than 1.

The next measurements to be considered were the spectral distributions of kinetic energy and enstrophy (Figures 11-18). The scalar energy spectrum and the scalar enstrophy spectrum were plotted on logarithmic scales at the initial time, 1512 time steps, and 3024 time steps. At the 1512th time step the source term was taken out of Equation (1). The 3024th time step was the final time step. The values of kinetic energy and enstrophy used in the spectral analysis were taken off the middle grid row, K=8. Since there were 25 grid points east-west, it was possible to obtain 12 wavenumbers. Components with wavenumbers greater than 6 are subject to possible distortion from aliasing errors.

In the initial spectra of kinetic energy and enstrophy, the energy and enstrophy were mainly contained in the even wavenumbers, which was due to the form of the initial stream field, and evenly distributed in these wavenumbers.

The zero dissipation, zero source experiment spectra had no discernible pattern other than a tendency for both energy



and enstrophy to be spread fairly evenly in all wavenumbers.

Experiment 2, where A was a constant, concentrated energy and enstrophy in the lower even wavenumbers without any distinctive pattern.

In experiment numbers 3, 4, and 5, there was a tendency for a -3 power slope to become apparent in the plots of the spectral variation. It was noted in the  $A_S$  form, as  $\gamma$  became smaller the spectral distribution tended to "bend" away from the -3 power slope. The dropoff at the large wavenumbers end of the spectrum also became more pronounced as  $\gamma$  became smaller. Obviously, the amount of energy and enstrophy present in corresponding wavenumbers was increased with decreasing  $\gamma$ .

Experiment numbers 6 and 7 had a sawtooth appearance with the even numbered waves generally containing more energy than the odd numbered waves. The envelope of the spectral distribution did have a tendency toward the -3 power slope, with the strongest tendency appearing at mid-time. Enstrophy tended to approach the -3 power slope more nearly than kinetic energy.

For a comparison of the effects of the different dissipation forms on the wave disturbances, the stream function field was analyzed at the initial time and after time steps 756, 1512, 2268, 3024 or approximately every 5 days (Figures 19-47). All experiments were started with the same initial  $\psi$  field. The zero dissipation, zero source experiment may be referenced in the figures.

After time step 756, the stream function field was beginning to become quite zonal in character. It appeared to have



primarily long wave components that were dominated by wavenumber 2. The strongest flow pattern was in the experiments with the smallest  $\gamma$  and in the A = constant case. Low areas were situated in the zonal band around the middle grid row, K=8. High areas were along the north-south boundaries.

At time step 1512, mid-time for all experiments, the flow pattern was very zonal. The low areas again were along the middle grid rows thereby causing easterly flow in the north and westerly flow in the south. The experiments with the most zonal flow were 7, 5 and 2. Leith's form of dissipation with  $\gamma$ =.5 produced the least zonal flow with a wave form more obvious than the other forms of dissipation.

After time step 2268, the flow is still predominately zonal; however, it had become weaker and was starting to deform in all experiments, the most notable cellular circulation being in  $A_{\text{T}}$  with  $\gamma = .5$ .

At the end-time of the experiments, the flow had considerably weakened. Leith's form of dissipation, with  $\gamma$ =.2 and the A=constant form stream function patterns were still very zonal in nature. Smagorinsky's forms deviated from the zonal flow more as the  $\gamma$  term decreased. The Smagorinsky form with  $\gamma_1$ =.13 had cellular circulation corresponding to about wavenumber 2. Leith's form with  $\gamma$ =.5 had the weakest flow pattern and the least zonal.



# V. CONCLUSIONS

Leith's form of dissipation was the fastest acting of the dissipation forms. All of the time-dependent curves reached their minimum value faster with  ${\bf A_L}.$  After the dissipative effect had leveled off the source term had become dominant and the  ${\bf A_L}$  forms had more of an opportunity to grow, with the smallest  $\gamma$  coefficients growing most rapidly. The spectral curves showed that  ${\bf A_L}$  had a tendency to form an envelope which approximately fit the -3 power slope. The variation in the constant  $\gamma$  in Leith's form of dissipation had the greatest influence on the stream field.

Smagorinsky's form for dissipation was not as fast acting as Leith's form. The Smagorinsky's form was also not as sensitive to the constant coefficient as was  $A_L$ , i.e., all measurements made with different  $\gamma$ 's indicated well behaved curves that related almost one to one with each other. For the  $A_S$  form, the spectral distributions between wavenumbers 1 to 6 fit the -3 power slope fairly well, with  $\gamma_1$ =.2 being the best fit. The stream function field for  $A_S$  was generally the least zonal of the forms of dissipation considered, with the strength of the flow inversely dependent upon the constant coefficients. The more zonal the flow, the stronger the gradients of the stream function appeared.

The constant form of A had the slowest reaction time in the time-dependence measurements as long as the source term was still in Equation (1). However,  $A_{C}$  produced the greatest



variations when the source term was removed in the time-dependence measurements. In the spectral measurements, the  $A_C$  form tended to have the -3 power slope in the even numbered waves only. The stream function field produced by  $A_C$  moved toward zonal flow at about the same rates as the other forms; however, once the zonal flow was established,  $A_C$  form kept the zonal flow more than the other forms.

Due to the simplicity of the model used in this study and the use of synthetic initial data, it is impossible to conclude which form of dissipation is the best in meteorological terms. However, this author believes that the differences in the experiments performed are great enough to justify further studies of this nature.

Additional experiments that appear desirable are the following:

First the expanding of the grid to investigate more wavenumbers.

Secondly, the addition of a linear drag term on the right hand side, namely,  $-K\zeta$ , to simulate the surface friction forces at work in the atmosphere.

Thirdly, and probably the most important, changing the source term to better simulate the baroclinic processes of the real atmosphere, with the source term having an effective wavenumber between 7 and 8.

It is expected that these variations to this model would produce a more realistic spectral distribution, and in accordance with two-dimensional turbulence theory. Hopefully,



the new formulation would produce a stream function field that was meteorologically meaningful.



#### APPENDIX A

## COMPLETE DESCRIPTION OF THE MODEL

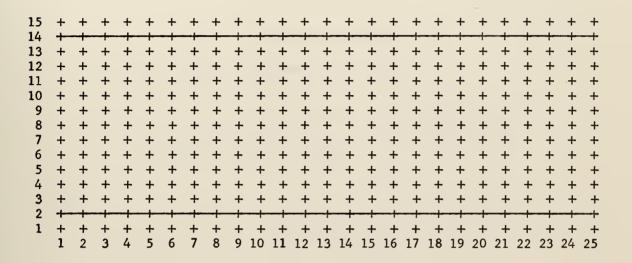


Figure 1. Grid for the model.

North-south direction has 15 grid points indexed with K. East-west direction has 25 grid points indexed with J. Distance between grid points was  $2.5^{\circ}$  latitude or 150 nautical miles ( $\Delta x = \Delta y = 2.5^{\circ}$ ). The grid is imposed on a constant  $\beta$  plane located at  $45^{\circ}$ N (K=8).

## BOUNDARY CONDITIONS

The southern boundary was placed at K=2 and the northern at K=14. The stream function was set equal to zero along these boundaries, i.e.

$$\psi(J,2) = \psi(J,14) = 0$$

To insure free slip on the northern and southern boundaries

$$\psi(J,1) = - \psi(J,3)$$

and

$$\psi(J, 15) = - \psi(J, 13)$$

was imposed on the model.



Periodicity was assumed in the east-west direction and achieved by:

$$\psi(1,K) = \psi(26,K)$$

and

$$\psi(25,K) = \psi(0,K)$$

## INITIAL CONDITIONS

The initial stream function was defined as:

$$\psi(\mathtt{J},\mathtt{K}) = - \ \mathtt{C} \ \sin \ (\frac{4 \, \mathrm{Ti} \mathtt{X}}{\mathtt{L}}) \ \sin \ (\frac{\mathrm{Ti} \mathtt{y}}{\mathtt{W}}) \ - \ \mathtt{C} \ \sin \ (\frac{8 \, \mathrm{Ti} \mathtt{X}}{\mathtt{L}}) \ \sin \ (\frac{\mathrm{Ti} \mathtt{y}}{\mathtt{W}})$$
 
$$- \ \mathtt{C} \ \sin \ (\frac{12 \, \mathrm{Ti} \mathtt{X}}{\mathtt{L}}) \ \sin \ (\frac{\mathrm{Ti} \mathtt{y}}{\mathtt{W}})$$

where

$$X = (J-1) \Delta x$$

$$J = 1, 2, \dots, 25$$

$$Y = (K-3) \Delta y$$

$$K = 3, 4, \dots, 16$$

$$W = 12 \Delta y$$

(width between north-south boundaries)

$$L = 2W \Delta x$$

(length of grid periodicity)

$$C = 1.0 \times 10^{7}$$

The source term was related to the stream function by

$$S = -S_0 \psi/C$$

where  $S_0 = 1.0 \times 10^{-10}$ .



#### APPENDIX B

# FINITE DIFFERENCE EQUATIONS

Equations (1), (2), and (3) are solved numerically by introducing finite-differences in x, y, and t. Sequential over-relaxation was used to solve for the  $\psi$  field and is discussed in Appendix C. Time differencing is discussed in Appendix D.

The vorticity, or the Laplacian of  $\psi$ , was approximated by the second-order expression using the center and four immediately contiguous points.

$$\zeta = \nabla^2 \psi = \left[ \psi(\mathtt{J} + \mathtt{1}, \mathtt{K}) + \psi(\mathtt{J} - \mathtt{1}, \mathtt{K}) + \psi(\mathtt{J}, \mathtt{K} + \mathtt{1}) + \psi(\mathtt{J}, \mathtt{K} - \mathtt{1}) - 4\psi(\mathtt{J}, \mathtt{K}) \right] / (\Delta \mathtt{x})^2 = \nabla \psi(\Delta \mathtt{x})^2$$

The numerical space-differencing method used on the non-linear term on the left hand side of Equation (1) is the second-order scheme developed by Arakawa (1966), which conserves kinetic energy and enstrophy within the nonlinear term.

The linear  $\beta$  term in Equation (1) was approximated by the first order difference equation

$$\beta \frac{\partial \psi}{\partial x} = \beta \left\{ [\psi(J+1,K) - \psi(J-1,K)]/2\Delta x \right\}$$



The above procedure was also used to find the finite difference form of the wind velocity components.

For the final term in Equation (1), an imaginary staggered grid had to be imposed. This half grid was needed because the finite differencing procedure limited the values obtainable. The form of the viscosity term was

$$\nabla \cdot (A\nabla \zeta) = \left\{ \left[ \zeta(J+1,K) - \zeta(J,K) \right] / \Delta x \right\} \quad \left\{ \left[ A(J+1,K) + A(J,K) \right] / 2 \right\}$$

$$- \left\{ \left[ \zeta(J,K) - \zeta(J-1,K) \right] / \Delta x \right\} \quad \left\{ \left[ A(J,K) + A(J+1,K) \right] / 2 \right\}$$

$$+ \left( \left\{ \left[ \zeta(J,K+1) - \zeta(J,K) \right] / \Delta y \right\} \quad \left\{ \left[ A(J,K+1) + A(J,K) \right] / 2 \right\}$$

$$- \left\{ \left[ \zeta(J,K) - \zeta(J,K-1) \right] / \Delta y \right\} \quad \left\{ \left[ A(J,K) + A(J,K+1) \right] / 2 \right\}$$



#### APPENDIX C

# RELAXATION TECHNIQUE

The equation to be solved for the  $\partial \psi/\partial t$  field from Equations (1) and (3) is

$$\nabla^2 \frac{\partial \psi}{\partial t} = F(x, y) \tag{C-1}$$

where

$$F(x,y) = J(\zeta,\psi) - \beta \frac{\partial \psi}{\partial x} + S + \nabla \cdot (A\nabla \zeta) , \qquad (C-2)$$

subject to the boundary conditions,  $\partial \psi / \partial t = 0$  on the north-south boundaries and periodic in the east-west direction.

In the numerical experiments, F(J,K) was computable on all interior grid points and the boundary conditions were known. Therefore, values of  $\partial \psi/\partial t(J,K)$  were determinable from the Poisson equation

$$\nabla^{2} \frac{\partial \psi}{\partial t} (J, K) = F_1(J, K)$$
 (C-3)

where

$$F_1(J,K) = \text{finite difference form of } F(J,K)(\Delta x)^2$$
 (C-4)

The first step in the iterative technique of sequential over-relaxation for the solution of Equation (C-3) was to make a first guess of values of  $\partial \psi/\partial t$  for every grid point to satisfy Equation (C-3). In these experiments this first guess after one step was zero everywhere; in subsequent steps the value from the previous time step was used for the guess field.

For every estimate of the solution, the residual is defined as follows:

$$R^{N}(J,K) \equiv \nabla^{2} \frac{\partial \psi}{\partial t}(N) - F_{1}(J,K)$$

where the superscript denotes the iteration.



A new estimate was made according to the formula:

$$\frac{\partial \psi}{\partial t}^{(N+1)}(J,K) = \frac{\partial \psi}{\partial t}^{(N)}(J,K) + \frac{(1+\alpha)}{4} R^{N}(\Delta x)^{2}$$

where  $\alpha$  is the overrelaxation coefficient and for these experiments equaled .65.

The iterations were continued until  $|R^N(J,K)| \le \varepsilon$  for all J,K, where  $\varepsilon$  was taken to be 1.0 x 10<sup>-13</sup> m<sup>2</sup> sec<sup>-1</sup> at which time the solution was considered to be sufficiently accurate.



#### APPENDIX D

## TIME STEP SCHEMES

In general, centered time differences (leapfrog) were used for all quantities; however, the first step was a Euler-backward time step.

The latter was also introduced every 50 time steps to selectively damp high frequency waves and to prevent the separation of solutions at even and odd time steps caused by the leapfrog time scheme.

## LEAPFROG SCHEME

$$\psi^{(t+1)}(J,K) = \psi^{(t-1)}(J,K) + 2\Delta t \frac{\partial \psi^{(t)}}{\partial t}(J,K)$$

where superscripts denote the time level.

#### EULER-BACKWARD

The Euler-backward is composed of two steps:

1. (forward step) 
$$\psi^{(t+1)*}(J,K) = \psi^{(t)}(J,K) + \Delta t \frac{\partial \psi}{\partial t}^{(t)}(J,K)$$
  
2. (simulated backward)  $\psi^{(t+1)}(J,K) = \psi^{(t)}(J,K) + \Delta t \frac{\partial \psi}{\partial t}^{(t+1)*}(J,K)$ 

Time steps were 10 minutes and a total of 3024 steps (about 3 weeks)
were taken in each experiment.



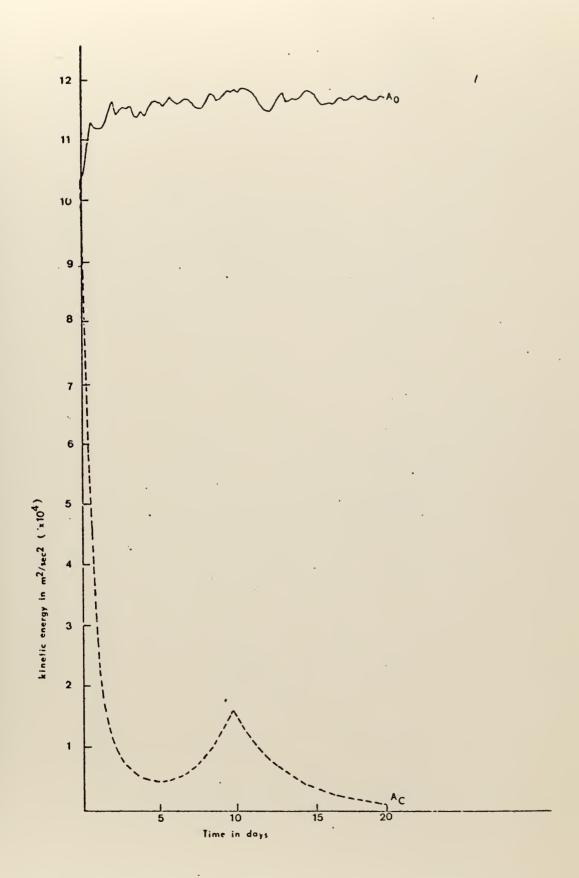


Figure 2. Total kinetic energy vs. time for the zero forcing and zero dissipation case and for A=constant form of dissipation



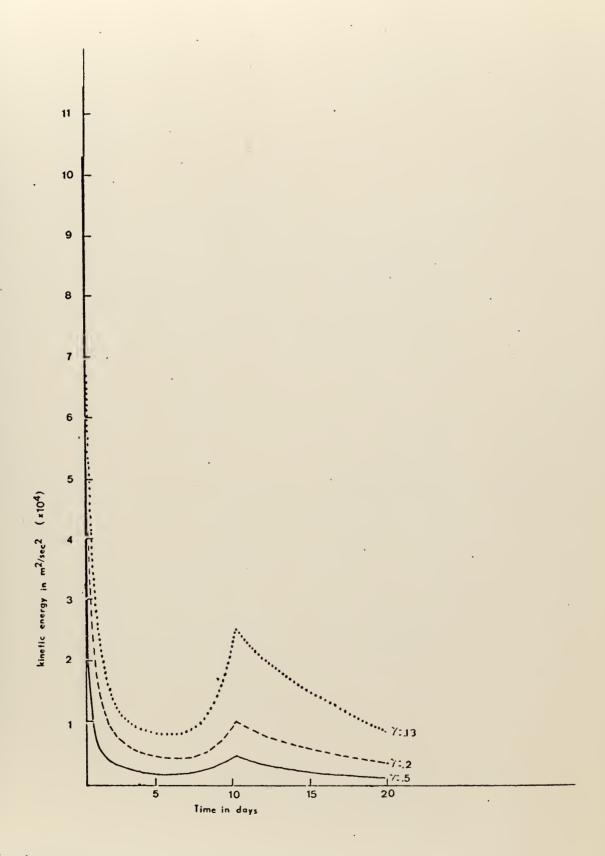


Figure 3. Total kinetic energy vs. time for the As form of dissipation with gamma=.5, .2, and .13



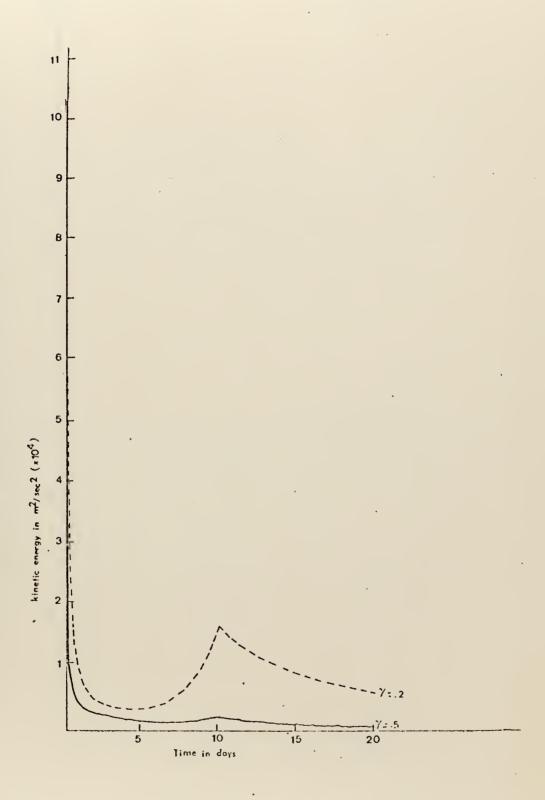


Figure 4. Total kinetic energy vs. time for the A<sub>I</sub> form of dissipation with gamma=.5 and .2.



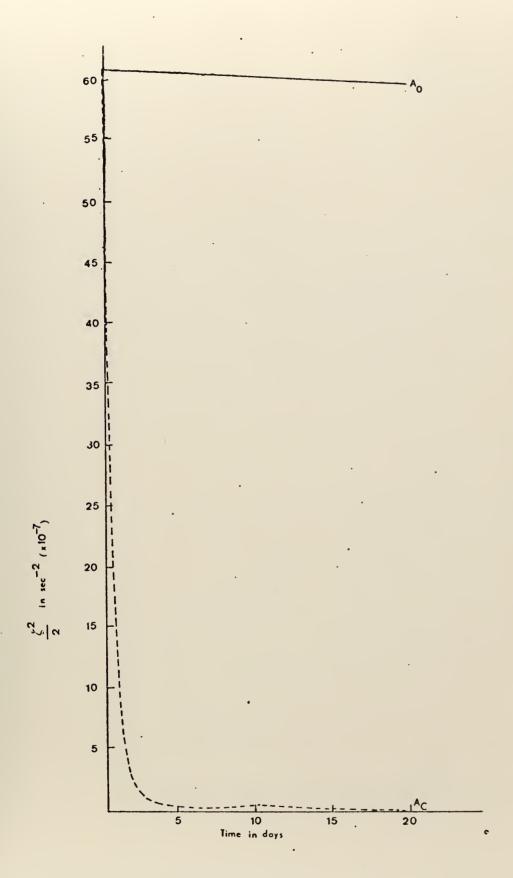


Figure 5. Total enstrophy vs. time for the zero forcing and zero dissipation case and for A=constant form of dissipation



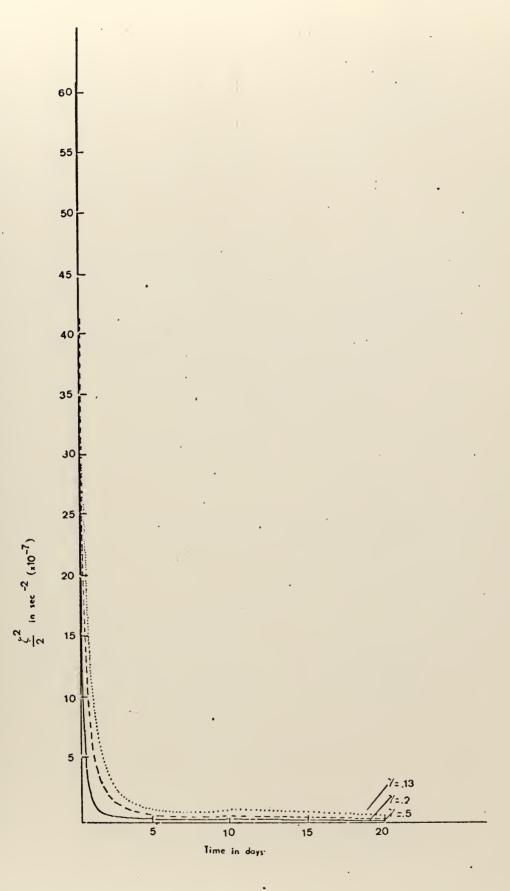


Figure 6. Total enstrophy vs. time for the A form of dissipation with gamma=.5, .2, and .13



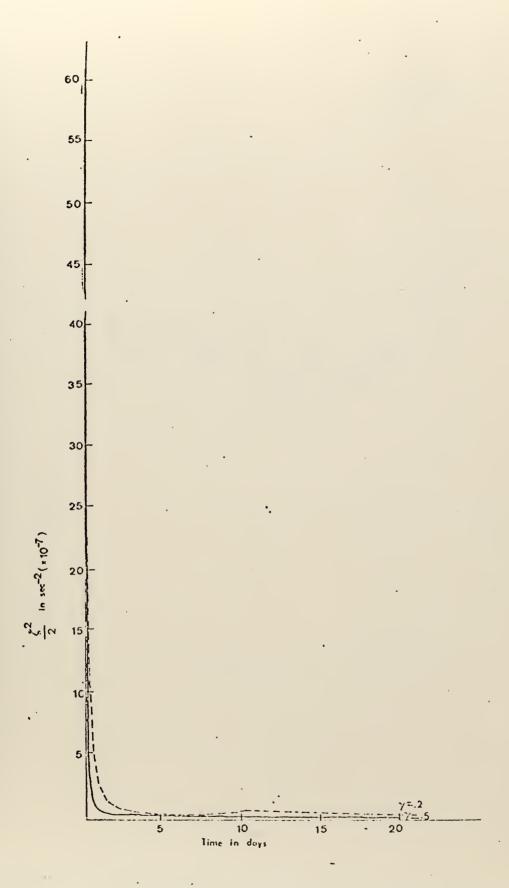


Figure 7. Total enstrophy vs. time for the  $A_{\rm L}$  form of dissipation with gamma=.5 and .2



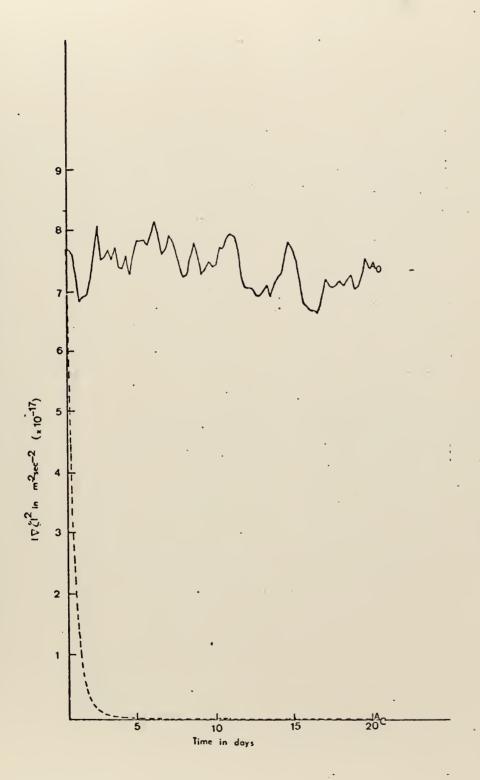


Figure 8. Total gradient of vorticity squared vs. time for the zero forcing and zero dissipation case and for A=constant form of dissipation



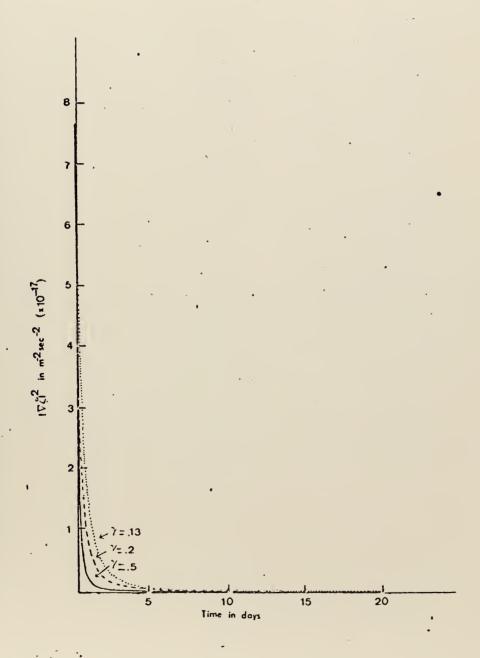


Figure 9. Total gradient of vorticity squared vs. time for the As form of dissipation with gamma=.5. 2, and .13



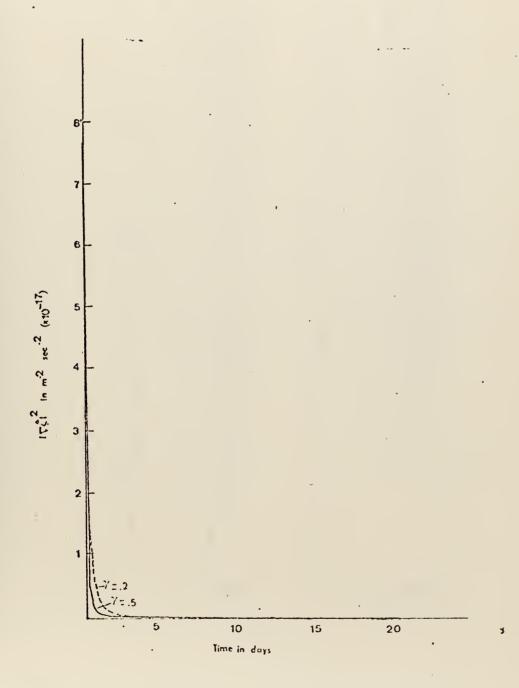


Figure 10. Total gradient of verticity squered vs. time for the A<sub>T</sub> form of dissipation with gamma=.5 and .2



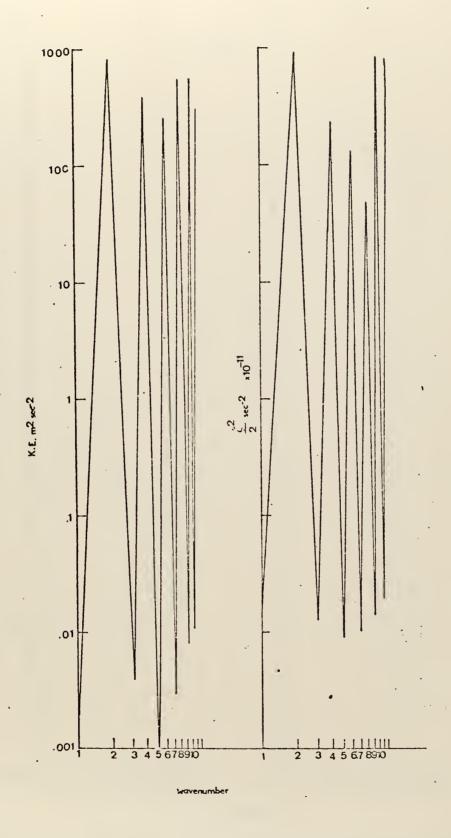


Figure 11. Initial spectral distribution of kinetic energy and enstrophy



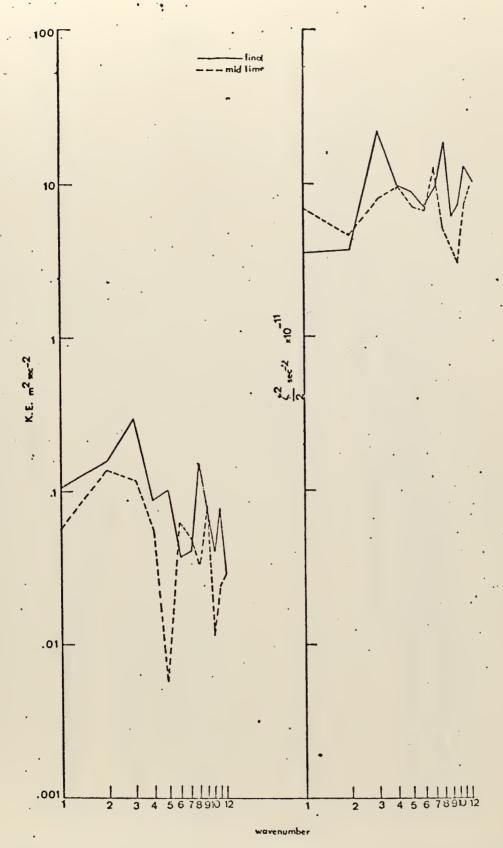


Figure 12. Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the zero dissipation and zero forcing case



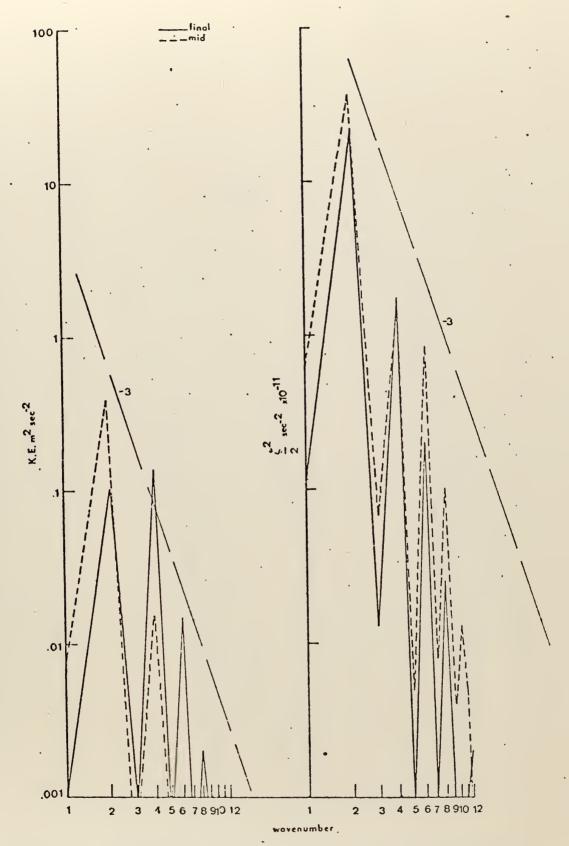


Figure 13. Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A=constant form of dissipation



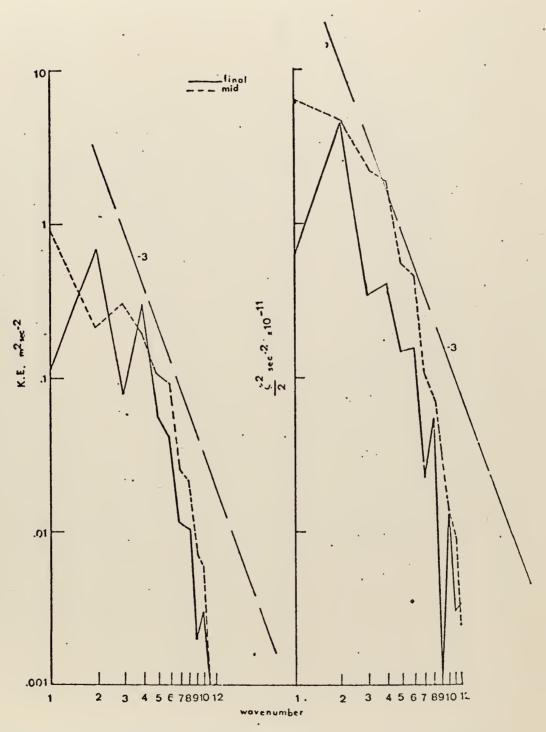


Figure 14. Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the As form of dissipation with gamma=.5



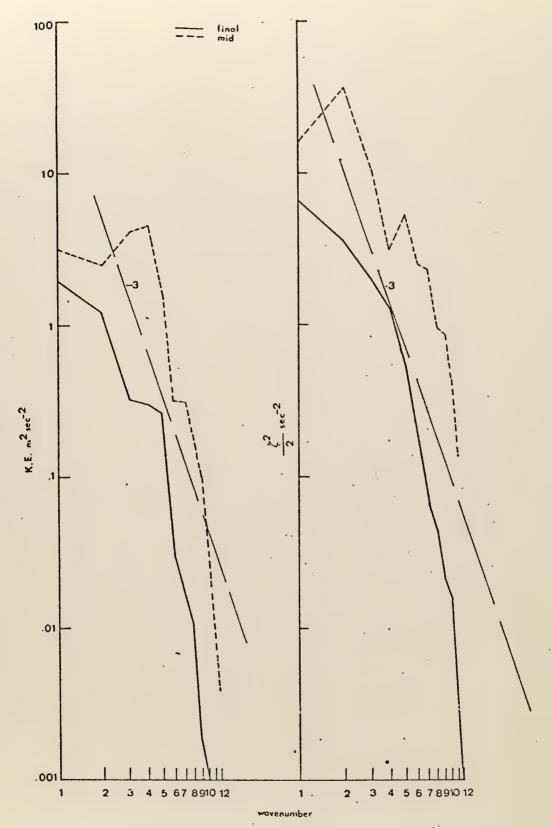


Figure 15. Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the As form of dissipation with gamma= .2



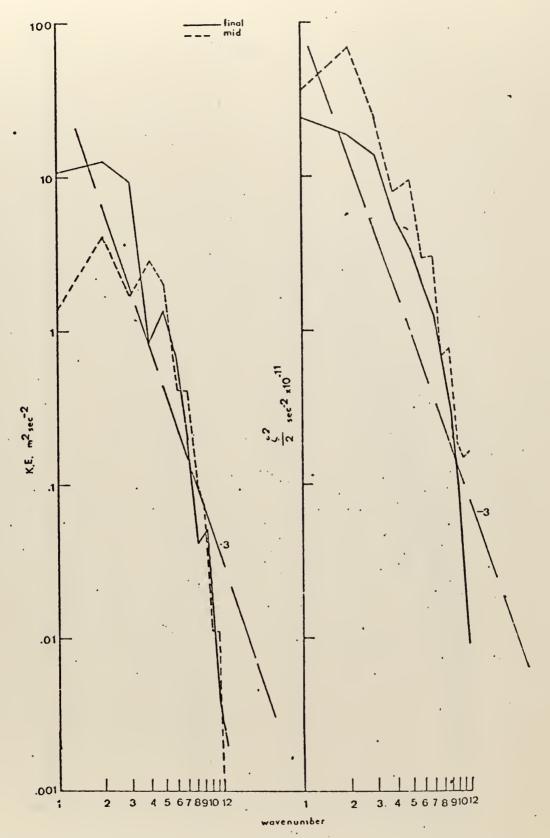


Figure 16. Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A<sub>s</sub> form of dissipation with gamma=



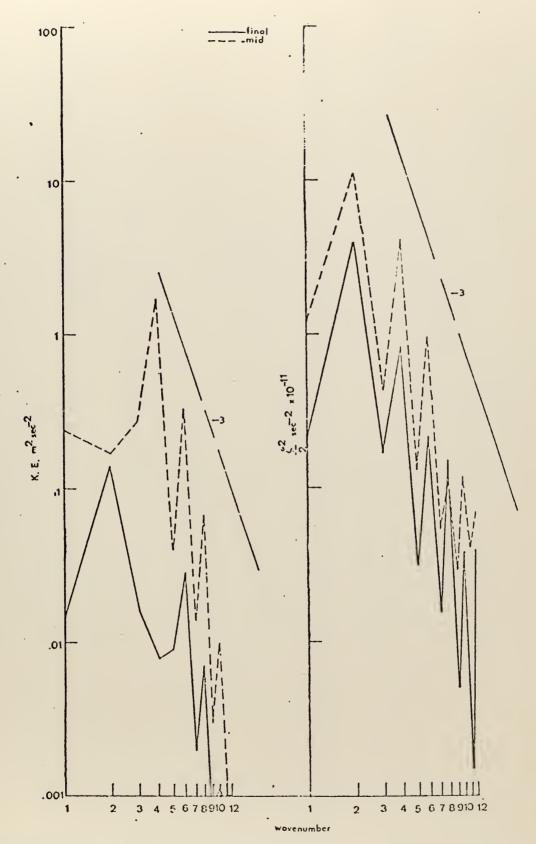


Figure 17. Spectral distribution of kinetic energy and enstrophy at mid-time and end-time for the A<sub>L</sub> form of dissipation with ground .5



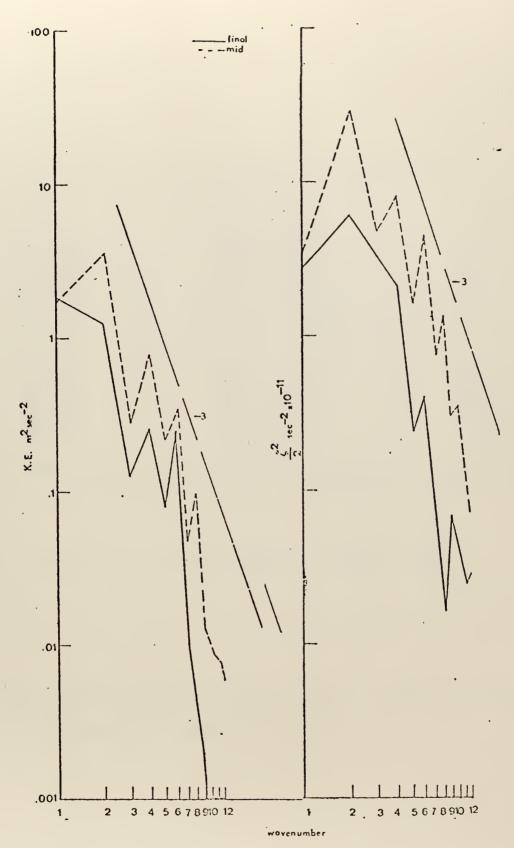


Figure 18. Spectral distribution of kinetic energy and enstrothy at mid-time and end-time for the A<sub>I</sub> form of dissipation with grands.



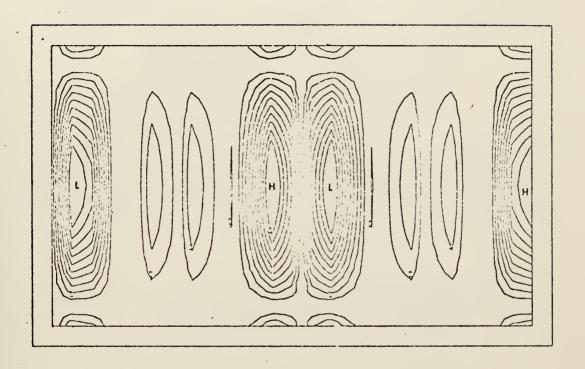


Figure 19. Initial stream function field

(All stream fields contoured from  $-2.0x10^7$  to  $+2.0x10^7$  in increments of  $.2x10^7$  m<sup>2</sup> sec<sup>-1</sup>)



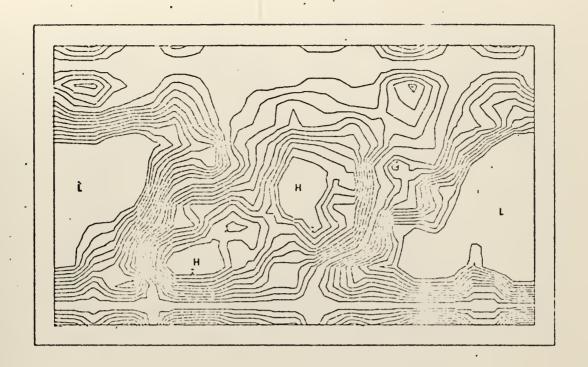


Figure 20. Stream function field at 5 days for zero forcing and zero dissipation case

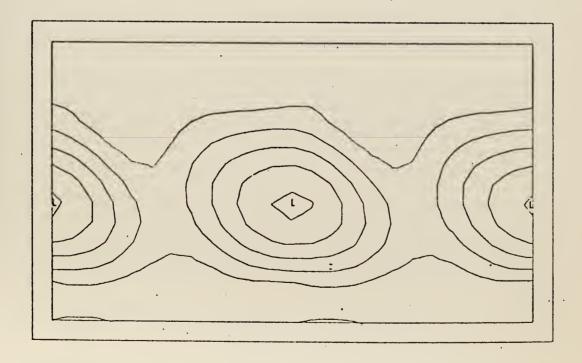


Figure 21. Stream function field at 5 days for A=constant form of dissipation



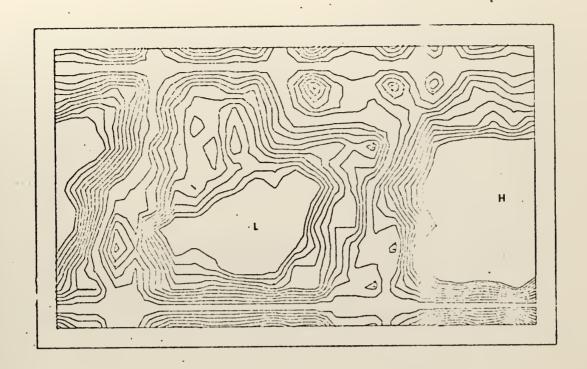


Figure 22. Stream function field at 10 days for zero forcing and zero dissipation case

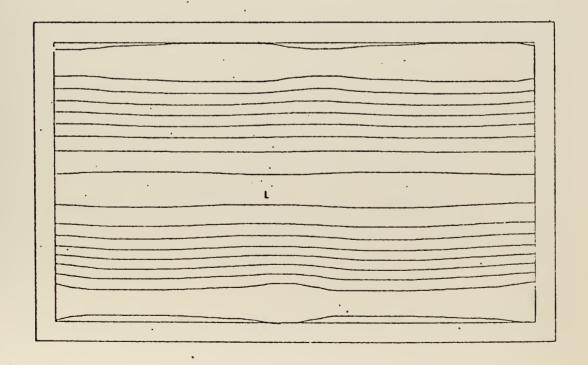


Figure 23. Stream function field at 10 days for A=constant form of dissipation



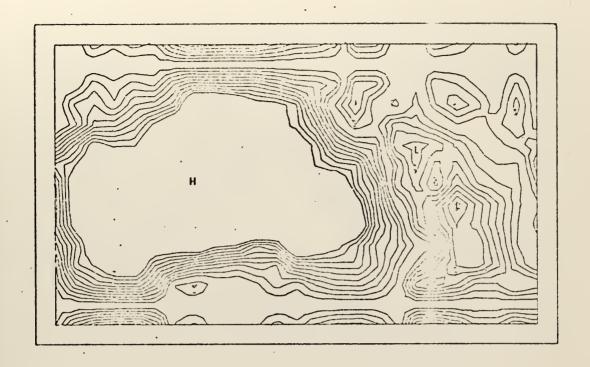


Figure 24. Stream function field at 15 days for zero forcing and zero dissipation case

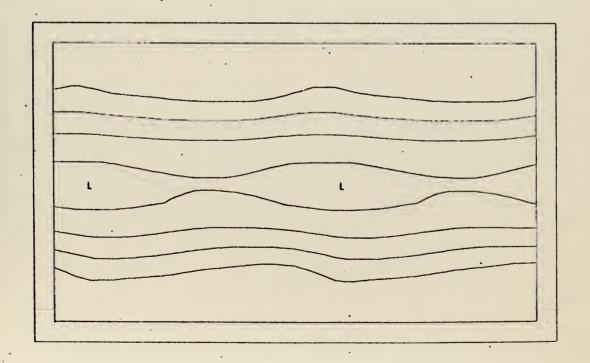


Figure 25. Stream function field at 15 days for A=constant form of dissipation



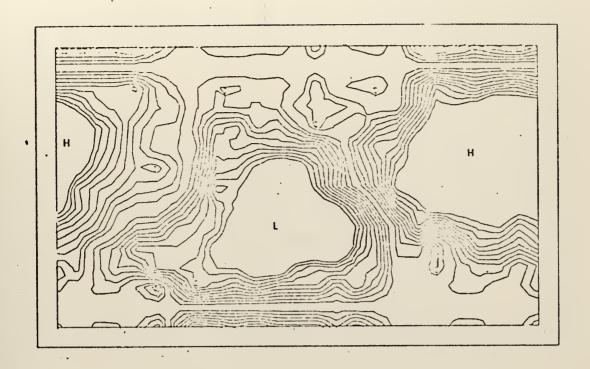


Figure 26. Stream function field at 20 days for zero forcing and zero dissipation case

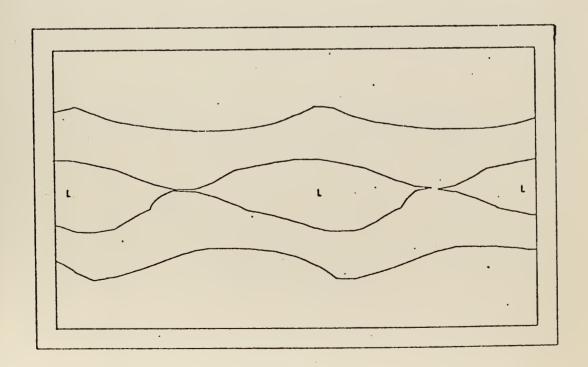


Figure 27. Stream function field at 20 days for A=constant form of dissipation



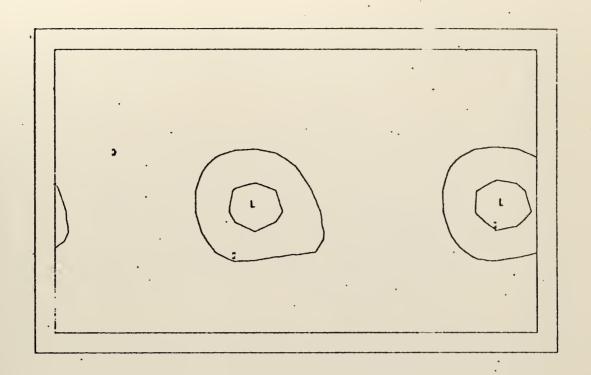


Figure 28. Stream function field at 5 days for  $\Lambda_L$  form of dissipation with gamma=.5

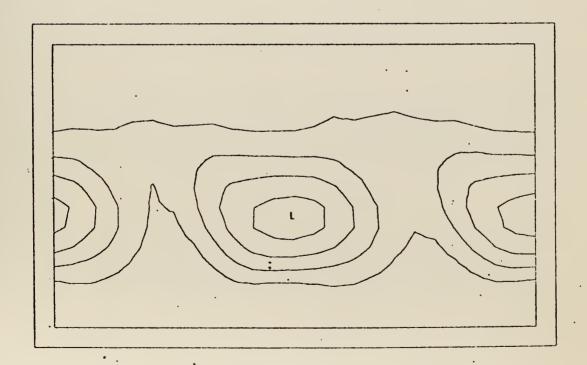


Figure 29. Stream function field at 5 days for A<sub>I</sub>, form of dissipation with garma=.2



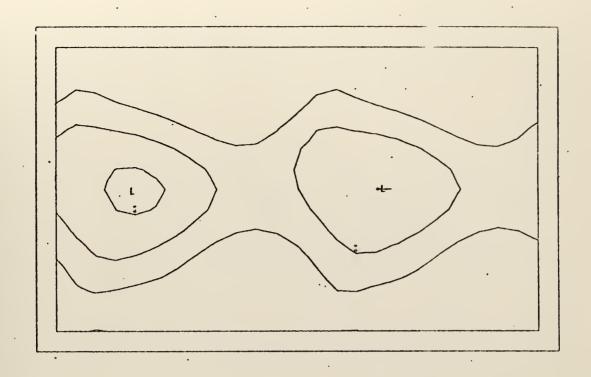


Figure 30. Stream function field at 10 days for  ${\rm A}_{\rm L}$  form of dissipation with gamma=.5

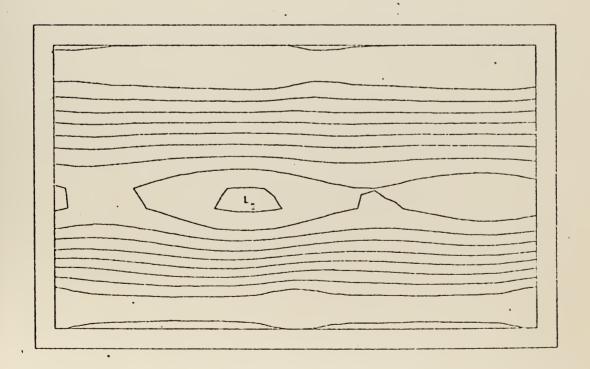


Figure 31. Stream function field at 10 days for  $\rm A_{L}$  form of dissipation with gamma=.2



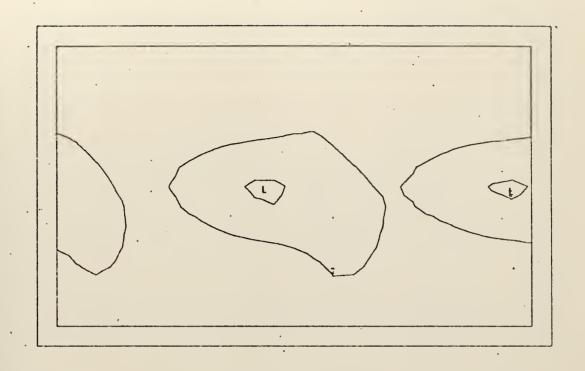


Figure 32. Stream function field at 15 days for  $\rm A_{L}$  form of dissipation with gamma=.5

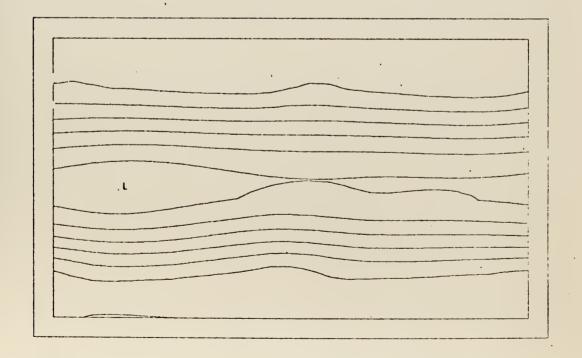


Figure 33. Streem function field at 15 days for  $A_{T_{\rm c}}$  form of dissipation with gamma=.2



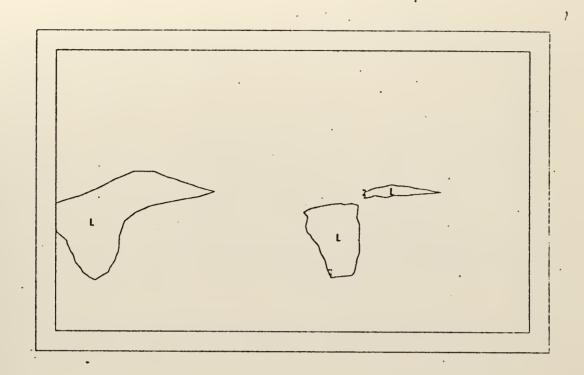


Figure 34. Stream function field at 20 days for  $\rm A_{L}$  form of dissipation with gamma=.5

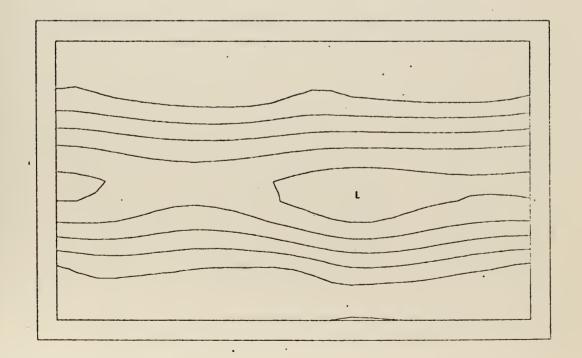


Figure 35. Stream function field at 20 days for  $\rm A_{L}$  form of dissipation with gamma=.2



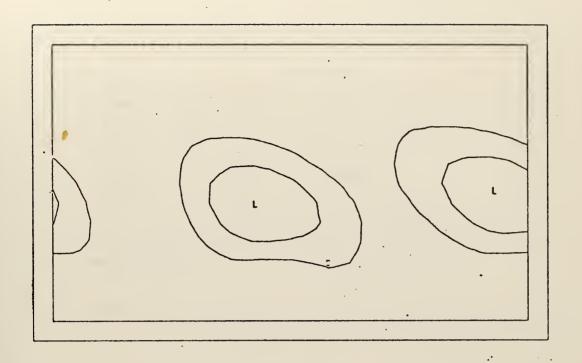


Figure 36. Stream function field at 5 days for  $A_s$  form of dissipation with gamma=.5

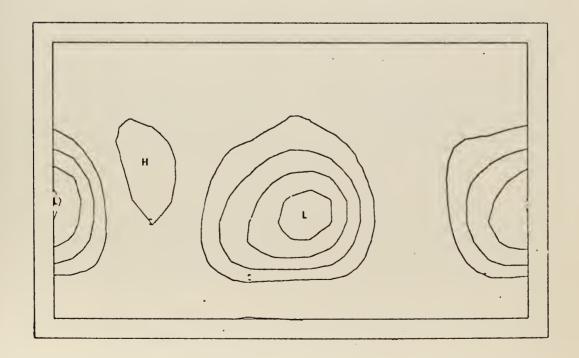


Figure 37. Stream function field at 5 days for As form of dissipation with gamma=.2



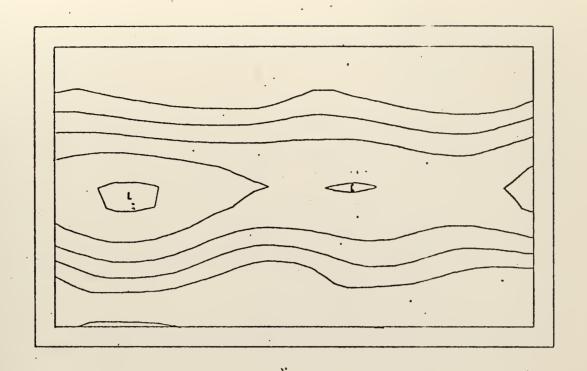


Figure 38. Stream function field at 10 days for  $A_s$  form of dissipation with gamma=.5

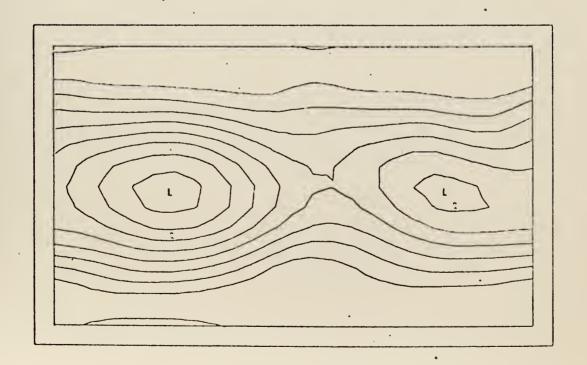


Figure 39. Stream function field at 10 days for  $A_s$  form of dissipation with gamma=.2



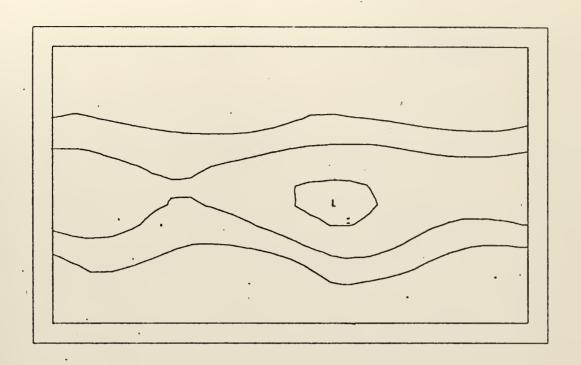


Figure 40. Stream function field at 15 days for As form of dissipation with gamma=.5

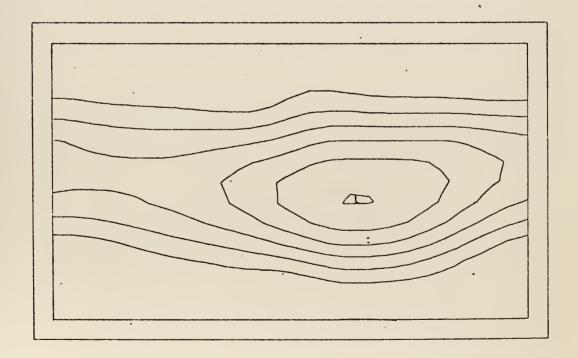


Figure 41. Stream function field at 15 days for As form of dissipation with gamma=.2



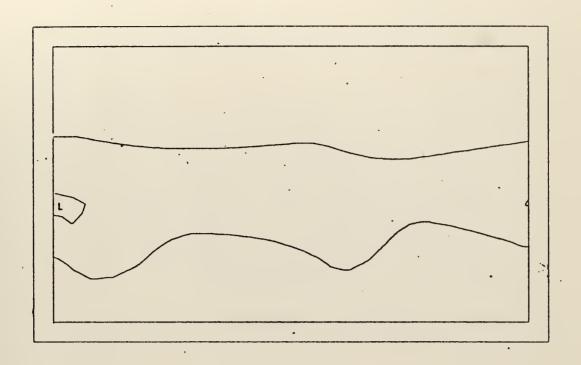


Figure 42. Stream function field at 20 days for  $A_s$  form of dissipation with gamma=.5

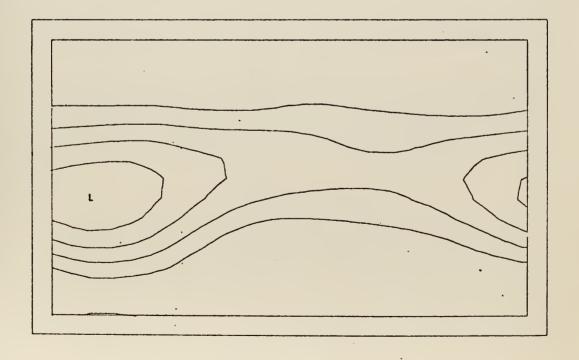


Figure 43. Stream function field at 20 days for As form of dissipation with gamma=.2



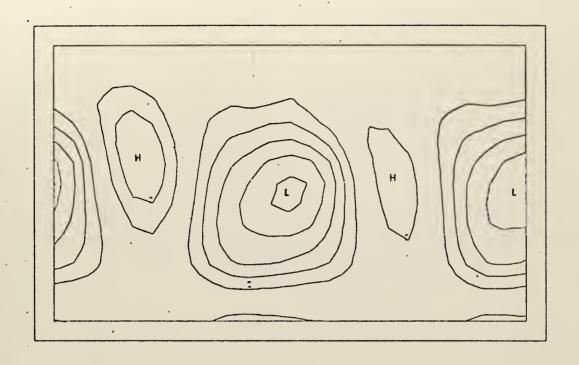


Figure 44. Stream function field at 5 days for As form of dissipation with gamma=.13

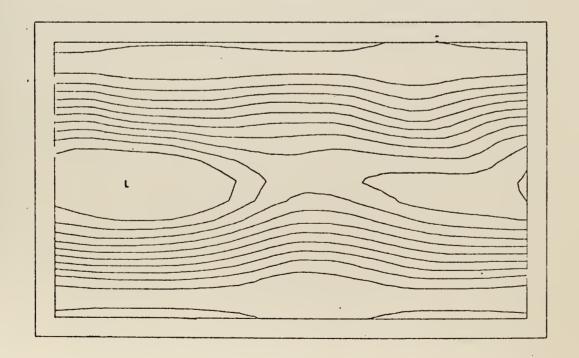


Figure 45. Stream function field at 10 days for As form of dissipation with gamma=.13



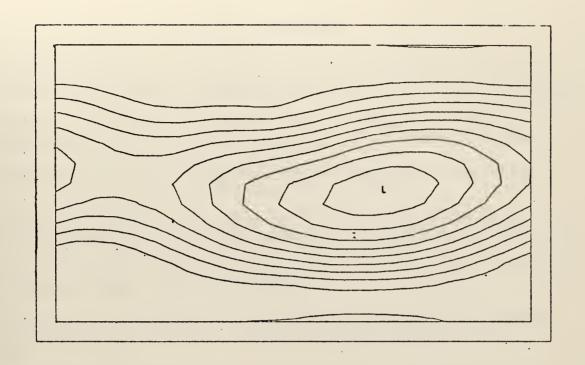


Figure 46. Stream function field at 15 days for  $A_s$  form of dissipation with gamma=.13

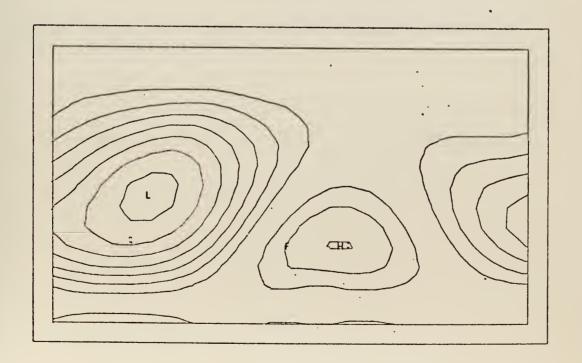


Figure 47. Stream function field at 20 days for As form of dissipation with gamma=.13



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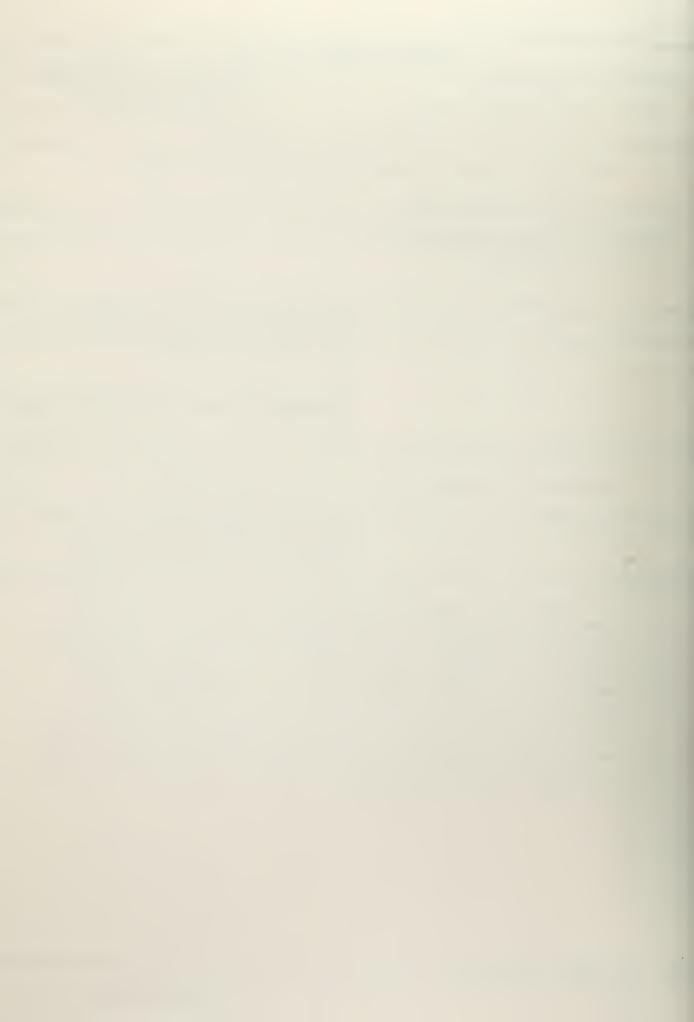
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11. SUPPLEMENTARY NOTES 12. SPONSORING MILITARY ACTIVITY Naval Postgraduate School Monterey, California 13. ABSTRACT

> Long term numerical integrations were performed on a two-dimensional model utilizing the barotropic vorticity equation including a space- and time-dependent forcing function and a laminar-type viscosity term. Three different forms of the laminar type viscosity or dissipation term were used. A comparison was made of the effects these different dissipation terms had on the time-dependence of total kinetic energy, total enstrophy, and total gradient of vorticity squared, the spectral distribution of kinetic energy and enstrophy, and the stream function field. difference of behavior of all the above variables was found for each form of dissipation.



Security Classification LINK A LINK B KEY WORDS ROLE ROLE ROLE Lateral viscosity

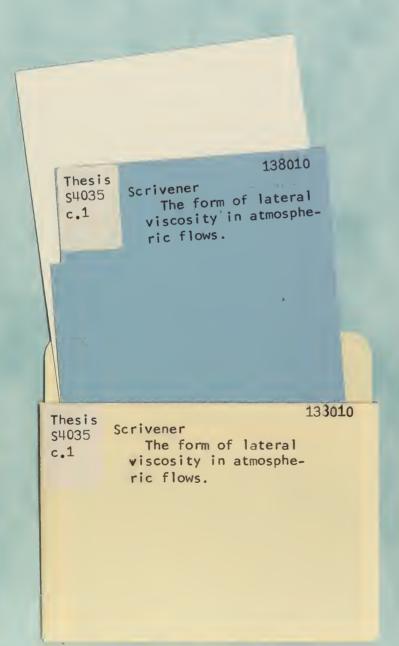
LINK C Dissipation Turbulence "Eddy Diffusion"

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